CSE 141L: Introduction to Computer Architecture Lab Microprocessor Architecture & ISAs

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CSE 141L

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Logistics Update: Waitlists

- This is a big, hard project class
 - You now have the full scope of the big, hard project

If you are considering dropping this course, <u>please</u> do so ASAP Please do not wait until the deadline [Friday!]

- If you are far back on the waitlist for 141, then please make room in 141L
- 141 will be offered next quarter
 - (I'm teaching it)

Logistics Updates

- Project spec released for the quarter
 - Skim the whole document
 - Read the all the requirements
 - Read Milestone 1 in depth
 - Read the all the requirements again
 - Focus on the programs to start what must your processor *do*?
- Milestone 1 is due in 16 days
- Viva la Zoom
 - Full remote through Jan 31 at least
 - Remote participation will always be an option for 141L this quarter

Logistics Advice

• Use Version Control

- This is how your group should share across machines
 - Shouldn't matter if you use Questa/ModelSim locally, CloudLabs, etc...
- Good feedback from folks using VSCode to edit & manage code
 - Especially as it has built-in git support
- Please no public repositories!

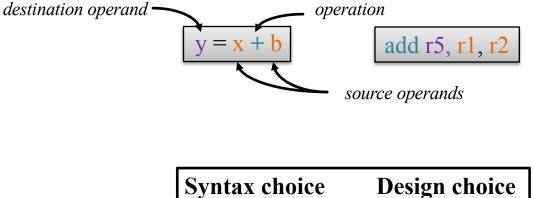
ISA Design and Processor Architecture are Interrelated

- Your ISA expresses what your processor can do
 - So your architecture has to be able to do it!

- that part of the architecture that is visible to the programmer
 - available instructions ("opcodes")
 - number and types of registers
 - instruction formats
 - storage access, addressing modes
 - exceptional conditions
- How do each of these affect your ISA design?

Key questions to ask when designing an ISA

- operations
 - how many?
 - which ones?
- operands
 - how many?
 - location
 - types
 - how to specify?
- instruction format ~
 - size
 - how many formats?

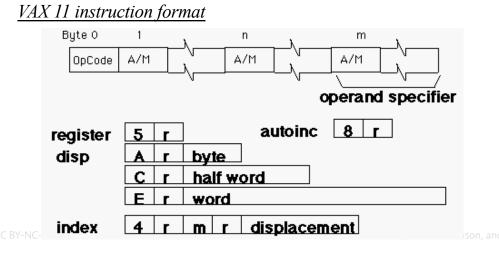


Syntax choice	Design choice
add r5, r1, r2	add r5, $r1-r4$
add [r1, r2], r5	

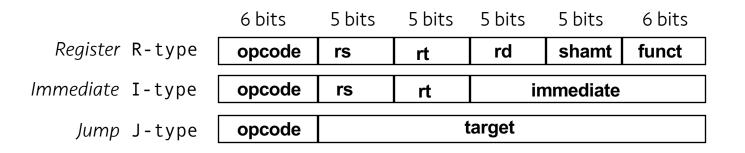
how does the computer know what 0001 0101 0001 0010 means?

Instruction Formats: What does each bit mean?

- Having many different instruction formats...
 - complicates decoding
 - uses more instruction bits (to specify the format)
 - Could allow us to take full advantage of a variable-length ISA not in 141L!

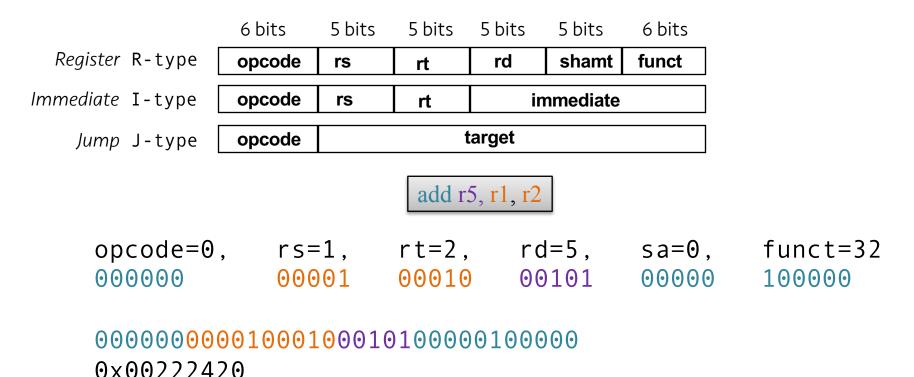


The MIPS Instruction Format



• the opcode tells the machine which format

Example of instruction encoding:



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Accessing the Operands aka, what's allowed to go here



- operands are generally in one of two places:
 - registers (32 options)
 - memory (2³² locations)
- registers are
 - easy to specify
 - close to the processor (fast access)
- the idea that we want to use registers whenever possible led to *load-store architectures*.
 - normal arithmetic instructions only access registers
 - only access memory with explicit loads and stores

	6 bits	5 bits	5 bits	5 bits	5 bits	6 bits	
Register R-type	opcode	rs	rt	rd	shamt	funct	
mmediate I-type	opcode	rs	rt	ir	nmediate		•
<i>Jump</i> J-type	opcode		1	target			

Poll Q: Accessing the Operands

There are typically two locations for operands: registers (internal storage - \$t0, \$a0) and memory. In each column we have which (reg or mem) is better.

Which row is correct?

	Faster access	Fewer bits to specify	More locations	
A	Mem	Mem	Reg	
В	Mem	Reg	Mem	
С	Reg	Mem	Reg	
D	Reg	Reg	Mem	
E	None of the above			

Q: How does all of this align with the project restrictions?

- [After class], re-read the restrictions with these slides in mind
- Design Question you must answer:
 - How will your ISA encode operations and operands?
 - And how will that impact how your machine operates?

How Many Operands? aka how many of these?



- Most instructions have three operands (e.g., z = x + y).
- Well-known ISAs specify 0-3 (explicit) operands per instruction.
- Operands can be specified implicitly or explicity.

Historically, many classes of ISAs have been explored, and trade off compactness, performance, and complexity

Style	# Operands	Example	Operation
Stack	Θ	add	$tos_{(N-1)} \leftarrow tos_{(N)} + tos_{(N-1)}$
Accumulator	1	add A	$acc \leftarrow acc + mem[A]$
General Purpose Register	3 2	add A B Rc add A Rc	$mem[A] \leftarrow mem[B] + Rc$ $mem[A] \leftarrow mem[A] + Rc$
Load/Store:	3	add Ra Rb Rc load Ra Rb store Ra A	$Ra \leftarrow Rb + Rc$ $Ra \leftarrow mem[Rb]$ $mem[A] \leftarrow Ra$

<u>Stack</u>	Accumulator	GP Register	GP Register
		(register-memory)	(load-store)

<u>Stack</u>	Accumulator	GP Register	GP Register
		(register-memory)	(load-store)
Push A			
Push B			
Add			
Pop C			

<u>Stack</u>	Accumulator	GP Register	GP Register
		(register-memory)	(load-store)
Push A	Load A		
Push B	Add B		
Add	Store C		
Pop C			

<u>Stack</u>	Accumulator	GP Register	GP Register
		(register-memory)	(load-store)
Push A	Load A	ADD C, A, B	
Push B	Add B		
Add	Store C		
Pop C			

<u>Stack</u>	Accumulator	GP Register	GP Register
		(register-memory)	(load-store)
Push A	Load A	ADD C, A, B	Load R1,A
Push B	Add B		Load R2,B
Add	Store C		Add R3,R1,R2
Pop C			Store C,R3

Exercise: Working through alternative ISAs [if time]

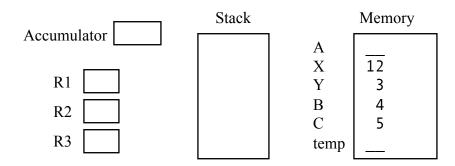
$$A = X^*Y - B^*C$$

Stack Architecture

Accumulator

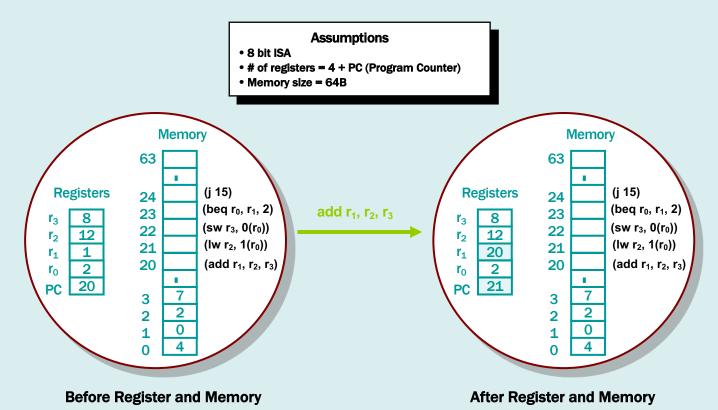
GPR

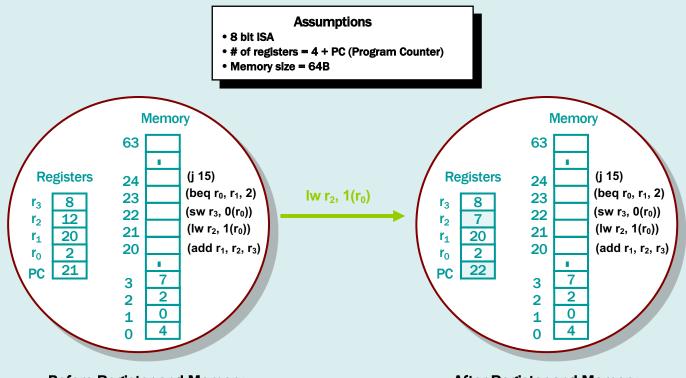
GPR (Load-store)



Example: load-store (aka register-register) ISA

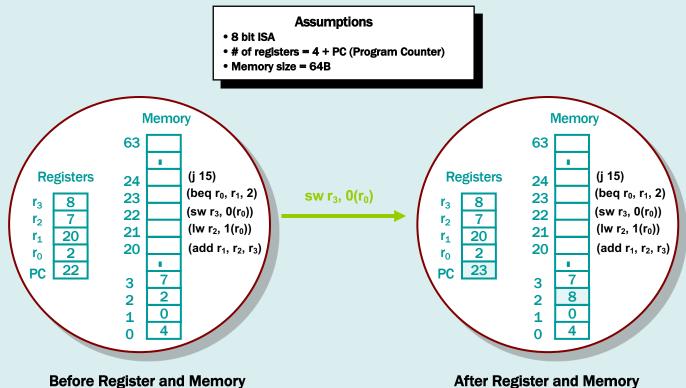
- load words from memory to reg file
- operate in reg file
- store results into memory from reg file



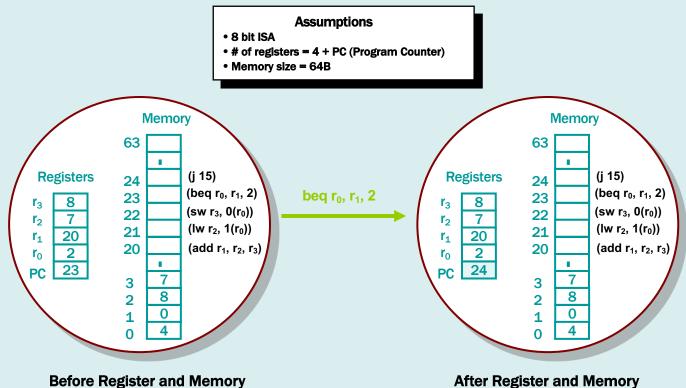


Before Register and Memory

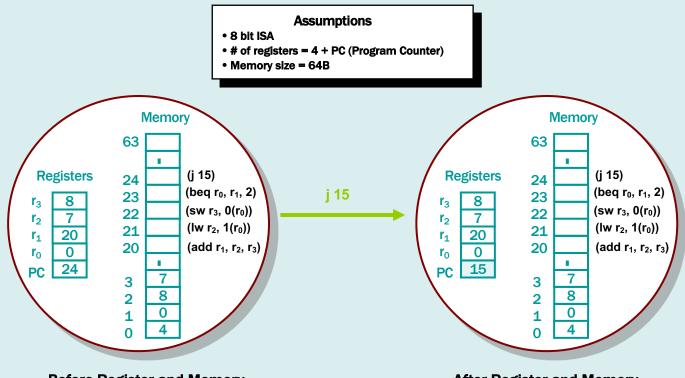
After Register and Memory



Before Register and Memory



Before Register and Memory



Before Register and Memory

After Register and Memory

Addressing Modes

aka: how do we specify the operand we want?

R3

#25

M[10000]

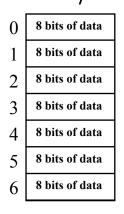
- Register direct
- Immediate (literal)
- Direct (absolute)
- Register indirect
- Base+Displacement
- Base+Index
- Scaled Index
- Autoincrement
- Autodecrement
- Memory Indirect

M[R3] M[R3 + 10000] M[R3 + R4] M[R3 + R4*d + 10000] M[R3++] M[R3 - -]

M[M[R3]]

What does memory look like anyway?

- Viewed as a large, single-dimension array, with an address.
- A memory address is an index into the array
- "Byte addressing" means that the index (address) points to a byte of memory.



<pre>module data_mem(</pre>	
input	CLK,
input	reset,
input [7:0]	DataAddress,
input	ReadMem,
input	WriteMem,
input [7:0]	DataIn,
<pre>output logic[7:0]</pre>	DataOut);
<pre>logic [7:0] core[2</pre>	56] ;

. . .

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Which kinds of things can a processor do?

- arithmetic
 - add, subtract, multiply, divide
- logical
 - and, or, shift left, shift right
- data transfer
 - load word, store word

"Control Flow" describes how programs execute

- Jumps
- Procedure call (jump subroutine)
- Conditional Branch
 - Used to implement, for example, if-then-else logic, loops, etc.
- Control flow must specify two things
 - Condition under which the jump or branch is taken
 - If take, the location to read the next instruction from ("target")

How do you specify the destination of a branch/jump?

- Unconditional jumps may go long distances
 - Function calls, returns, ...
- Studies show that almost all conditional branches go short distances from the current program counter
 - loops, if-then-else, ...
- A relative address requires (many) fewer bits than an absolute address
 - e.g., beq \$1, \$2, 100 => if (\$1 == \$2): PC = (PC+4) + 100 * 4

MIPS in one slide

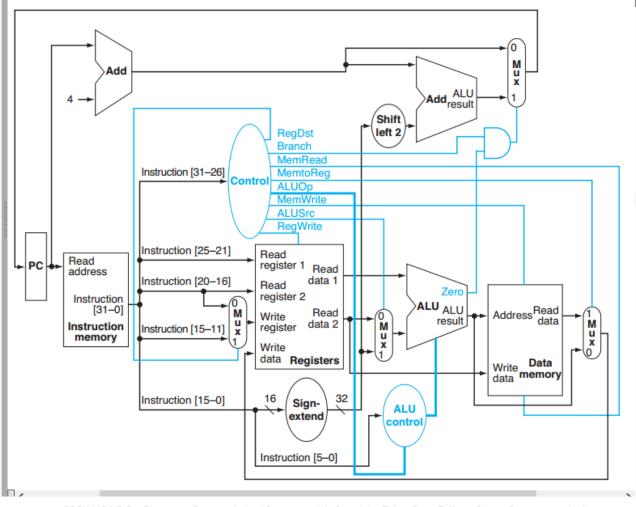
MIPS operands

Name	Example	Comments	
	\$s0-\$s7, \$t0-\$t9, \$zero,	Fast locations for data. In MIPS, data must be in registers to perform	
32 registers	\$a0-\$a3, \$v0-\$v1, \$gp,	arithmetic. MIPS register \$zero always equals 0. Register \$at is	
	\$fp, \$sp, \$ra, \$at	reserved for the assembler to handle large constants.	
	Memory[0],	Accessed only by data transfer instructions. MIPS uses byte addresses, so	
2 ³⁰ memory	Memory[4],,	sequential words differ by 4. Memory holds data structures, such as arrays,	
words	Memory[4294967292]	and spilled registers, such as those saved on procedure calls.	

MIPS assembly language

Category	Instruction	Example	Weaning	Comments
	add	add \$s1, \$s2, \$s3	\$s1 = \$s2 + \$s3	Three operands; data in registers
Arithmetic su	subtract	sub \$s1, \$s2, \$s3	\$s1 = \$s2 - \$s3	Three operands; data in registers
	add immediate	addi \$s1, \$s2, 100	\$s1 = \$s2 + 100	Used to add constants
	load word	lw \$s1, 100(\$s2)	\$s1 = Memory[\$s2+100]	Word from memory to register
	store word	sw \$s1, 100(\$s2)	Memory[\$s2+100] = \$s1	Word from register to memory
Data transfer	load byte	lb \$s1, 100(\$s2)	\$s1 = Memory[\$s2+100]	Byte from memory to register
	store byte	sb \$s1, 100(\$s2)	Memory[\$s2+100] = \$s1	Byte from register to memory
	load upper immediate	lui \$s1, 100	\$s1 = 100 * 2 ¹⁶	Loads constant in upper 16 bits
	branch on equal	beq \$s1, \$s2, 25	if (\$s1 == \$s2) go to PC + 4 + 100	Equal test; PC-relative branch
Conditional	branch on not equa	bne \$s1, \$s2, 25	if (\$s1 != \$s2) go to PC + 4 + 100	Not equal test; PC-relative
branch .	set on less than	slt \$s1, \$s2, \$s3	if(\$s2 < \$s3) \$s1 = 1; else \$s1 = 0	Compare less than; for beq, bne
	set less than imme diate	slti \$s1, \$s2, 100	if(\$s2 < 100) \$s1 = 1; else \$s1 = 0	Compare less than constant
	jump	j 2500	go to 10000	Jump to target address
Uncondi-	jump register	jr \$ra	goto \$ra	For switch, procedure return
tional jump	jump and link	jal 2500	\$ra = PC + 4; go to 10000	For procedure call

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More Information? More Machine Types?

- 141 will talk some about other machine types
 - The 141 textbook goes into more detail
- I will post a collection of slides and resources from others in Canvas
- Many additional resources online